# Frontier Topics in Empirical Economics: Week 2 Non-parametric Method 

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Non-parametric Method: Introduction

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■ Common Parametric Models
Linear Model: $y=X^{\prime} \beta+e, e \sim N\left(0, \sigma^{2}\right)$;
Probit/Logit Model: $P(y \mid X)=G(X \beta)$ where G is a nonlinear function

- Explicit Parametric Structure for Distribution
- Common Estimator

OLS, MLE, Nonlinear LS, Efficient GMM etc.

- Key Properties of the Estimator

Consistency, BLUE, Asymptotic Efficiency etc.

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- Why linear? Simple? Why not $y=x^{3} \cdot \operatorname{In} x+e$ ?
- What if linear specification is wrong?
- Everything collapses. No data can save
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- For example, if true model is Logit, but not linear regression


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- Realizations are given (sample), they are NOT random in our context $\int x \sum_{i}^{n} X_{i} d x=\sum_{i}^{n} X_{i} \int x d x$


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- Instead of assuming $E\left(y_{i} \mid x_{i}\right)=x_{i} \beta$, we consider this CEF point by point
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. In general, we have an estimation of $F(x)$ as:


- The proportion of points (realizations) that are smaller than $x$


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- Consider estimating a probability density function (PDF)
- PDF represents a marginal increase in CDF at some point (derivative)

- Changes of $F(x)$ in a very small interval (with length $2 h$ )
- $h$ is called "bandwidth"


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- Then we can write the probability density $f(x)$ at some value $x$ as:

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- How to interpret this?
- We count the number of obs within a small interval around $x$, dividing by the length and the total number of obs
- $\sum_{i=1}^{n} \frac{1}{2 h} 1\left(x-h \leq X_{i} \leq x+h\right)$ is the number of obs per unit length
- When $n$ is large, we can choose very small $h$


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\hat{f}(x)=\frac{1}{n} \sum_{i=1}^{n} \frac{1}{h} k\left(\frac{X_{i}-x}{h}\right)
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- We call $k(v)$ a uniform kernel function
- This $\hat{f}(x)$ is a kernel estimator of the PDF (uniform kernel)
- Kernel is weight!
- There can be other kinds of kernel functions, when we assign different weights to different observations


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- $k(v)$ is integrated to 1
- $k(v)$ is symmetric with $k(v)=k(-v)$
- The weights sum to one; The weights are symmetric to the left and to the right
- Triangular Kernel: $k(v)=(1-|v|) 1(|v| \leq 1)$
- Epanechnikov Kernel: $k(v)=\frac{3}{4}\left(1-v^{2}\right) \mathbf{1}(|v| \leq 1)$
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Figure 1: Various Kernels

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■ For multivariate case, let $v=\left(v_{1}, v_{2}, \cdots, v_{q}\right)$.

- Define product kernel: $K(v)=k\left(v_{1}\right) k\left(v_{2}\right) \cdots, k\left(v_{q}\right)$
- The estimator becomes:

$h=\left(h_{1}, h_{2}, \cdots, h_{q}\right)$


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## Non-parametric Method: Kernel Regression

■ For multivariate case, let $v=\left(v_{1}, v_{2}, \cdots, v_{q}\right)$.

- Define product kernel: $K(v)=k\left(v_{1}\right) k\left(v_{2}\right) \cdots, k\left(v_{q}\right)$.
- The estimator becomes:

$$
\hat{f}(x)=\frac{1}{n h_{1} h_{2} \cdots, h_{q}} \sum_{i} K\left(\frac{X_{i}-x}{h}\right)
$$

■ $h=\left(h_{1}, h_{2}, \cdots, h_{q}\right)$

Non-parametric Method: Kernel Regression


## Non-parametric Method: Kernel Regression

## Step 3: Estimating a CEF

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- Based on the CDF and PDF we've got, we have Nadaraya-Watson Estimator (N-W) for CEF as follows:

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\hat{g}(x)=\sum_{i=1}^{n} Y_{i} K_{h}\left(X_{i}-x\right) \quad \text { where } \quad K_{h}\left(X_{i}-x\right)=\frac{K\left(\frac{X_{i}-x}{h}\right)}{\sum_{i=1}^{n} K\left(\frac{X_{i}-x}{h}\right)}
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n Intuition: The conditional Expectation of Y given $\mathrm{X}=\mathrm{x}$ is estimated as a weighted average of observed $Y_{i}$ closely around $\times$ (within the range of bandwidth h)

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## Homework

## Non-parametric Method: Kernel Regression

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■ 1. Derive NW Estimator from the kernel estimator of CDF and PDF. This can be a little bit hard. You can refer to Notes from Carol (or Hansen's book) for help.

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## Non-parametric Method: Kernel Regression

- We have $g(x)=E(Y \mid X)$ as CEF and $f(x)$ as density for $x$


## Theorem (Asymptotics for $\mathrm{N}=\mathrm{W}$ - Estimator)

Under some regularity conditions, as $n \rightarrow \infty, h_{s} \rightarrow 0(s=1, \ldots, q), n h_{1} \ldots h_{q} \rightarrow \infty$ and $n h_{1} \ldots h_{q} \sum_{s=1}^{q} h_{s}^{6} \rightarrow 0$, we have:

$$
\begin{gathered}
\sqrt{n h_{1} \ldots h_{q}}\left(\hat{g}(x)-g(x)-\sum_{s=1}^{q} h_{s}^{2} B_{s}(x)\right) \xrightarrow{d} N\left(0, \frac{\sigma^{2}(x)}{f(x)}\left(\int k(v)^{2} d v\right)^{q}\right) \\
\text { where } B_{s}(x)=\frac{\int v^{2} k(v) d v}{2 f(x)}\left[2 \frac{\partial f(x)}{\partial x_{s}} \frac{\partial g(x)}{\partial x_{s}}+f(x) \frac{\partial^{2} g(x)}{\partial x_{s}^{2}}\right]
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- (3) Kernel more concentrated $\Rightarrow$ Bias ! $\left(\int v^{2} k(v) d v\right)$, Variance $\left.\uparrow\left(\int k(v)^{2} d v\right)\right)$
- (4) Slope Effect and Curvature Effect on bias: $\frac{\partial f(x)}{\partial x_{s}} \frac{\partial g(x)}{\partial x_{s}}, \frac{\partial^{2} g(x)}{\partial x_{s}^{2}}$
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Non-parametric Method: Local Polynomial

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- Another widely used kernel-based method is local polynomial
- In linear regression, we use a global linear function to fit data
- In local polynomial, we use piece-wise polynomial (linear) function to fit data interval by interval


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For some $X=x$, we fit $g(x)$ by choosing samples very close to $x$. Then we fit a polynomial for these observations. (Here, linear)

Non-parametric Method: Local Polynomial

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- For $g(x)$, we solve the following optimization problem at each point $x$ :
$\min _{b_{0}, b_{1}, \cdots, b_{p}} \sum_{i=1}^{n} k\left(\frac{X_{i}-x}{h}\right)\left(Y_{i}-b_{0}-b_{1}\left(X_{i}-x\right)-b_{2}\left(X_{i}-x\right)^{2}-\cdots-b_{p}\left(X_{i}-x\right)^{p}\right)^{2}$
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# Non-parametric Method: Series-based Methods 

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■ Both kernel and local polynomial regressions are Kernel-based methods

- There are three disadvantages of this method:
- Series-based methods alleviate these problems


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g(X)=\sum_{k=0}^{\infty} \frac{g^{(k)}(0)}{k!} X^{k}
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- We can use OLS to estimate this polynomial
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## Non-parametric Method: Series-based Methods

■ Runge's phenomenon

- Red: original function; Blue: fifth-order poly; Green: ninth-order poly

- Since the power polynomials are forced to vary somewhere
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- We will discuss this problem in details in the next lecture

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- There are more basis
- Such as Spline basis and Wavelet basis
- They are complicated, rarely seen in Applied works
- But Carol claims that Spline basis is in general a better choice
- If interested, you can read her notes


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- Totally data driven, no prior information
- Convergence rate is low, variance is high, requirement for data is high
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- $E(Y \mid Z)$ and $E(X \mid Z)$ can be estimated using methods introduced previously
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- A better chioce is "percentile interval'
- First, we stack the sample of bootstran estimates $\left\{\hat{\beta}^{1}, \hat{\beta}^{2}, \ldots . \hat{\beta}^{R}\right\}$
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■ Paper report
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