Frontier Topics in Empirical Economics: Week 2 Non-parametric Method

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- Common Parametric Models Linear Model: $y = X'\beta + e$, $e \sim N(0, \sigma^2)$; Probit/Logit Model: $P(y|X) = G(X\beta)$ where G is a nonlinear function
- Explicit Parametric Structure for Distribution
- Common Estimator
 OLS, MLE, Nonlinear LS, Efficient GMM etc.
- Key Properties of the Estimator Consistency, BLUE, Asymptotic Efficiency etc.

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- In linear model, we have to assume that CEF is linear
- Why linear? Simple? Why not $y = \beta x^{3\gamma} \cdot \ln x + e$?
- What if linear specification is wrong?
- Everything collapses. No data can save.
- It becomes only a linear approximation
- For example, if true model is Logit, but not linear regression
- Functional form can be wrong

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- Potential Outcome Framework is intrinsically non-parametric
- If we can directly get estimations of E[y|x=1] and E[y|x=0]
- We can estimate the ATE/ATT in a more general way without regression
- There are many other statistical modeling methods
- Non-parametric, semi-parametric to estimate CEF directly
- To understand tools beyond linear regression

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- Notation: x_i, y_i denotes random variable; X_i, Y_i denotes realizations; x, y denotes random variables or some value of the random variables
- Realizations are given (sample), they are NOT random in our context $\int x \sum_{i=1}^{n} X_{i} dx = \sum_{i=1}^{n} X_{i} \int x dx$

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- Let's consider the first non-parametric method: Kernel regression
- It is super intuitive and interesting
- Instead of assuming $E(y_i|x_i) = x_i^i\beta$, we consider this CEF point by points
- That is, estimate $E(y_i|x_i)$ for each possible point of $x_i = x_i$

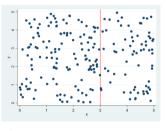
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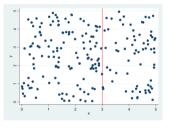
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Step 1: Estimating a cumulative density



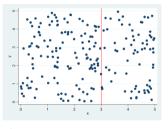
- What is the CDF at x = 3? $\hat{F}(x = 3) = ?$
- Go back to kindergarten
- What is the probability of drawing $x \le 3$?
 - \Rightarrow How many points are there to the left of 3 (compare to all points)

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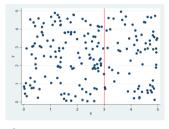
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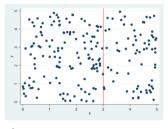
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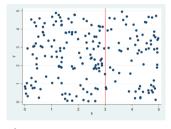
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$$\hat{\Xi}(x=3) = \frac{1}{n} \sum \mathbf{1}(X_i \le 3)$$

 \blacksquare In general, we have an estimation of F(x) as

$$F(x) = P(X \le x) \Rightarrow \hat{F}(x) = \frac{1}{n} \sum_{i=1}^{n} \mathbf{1}(X_i \le x)$$

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- PDF represents a marginal increase in CDF at some point (derivative)

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$$= \frac{1}{n} \sum_{i=1}^{n} \frac{1}{2h} \mathbf{1}(x - h \le X_i \le x + h)$$

- How to interpret this?
- \blacksquare Count the number of obs within a small interval around x, dividing by the length and the total number of obs
- $\sum_{i=1}^n \frac{1}{2h} \mathbf{1}(x-h \le X_i \le x+h)$ is the number of obs per unit length
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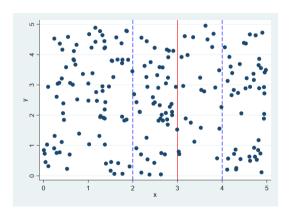
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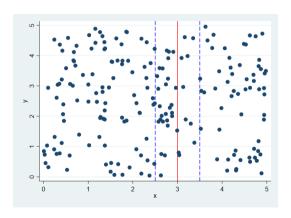


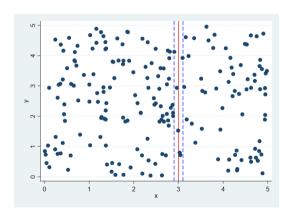
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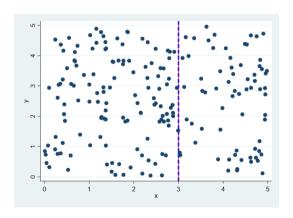
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$$\hat{f}(x) = \frac{1}{n} \sum_{i=1}^{n} \frac{1}{h} k(\frac{X_i - x}{h})$$

- We call k(v) a uniform kernel function
- \blacksquare This $\hat{f}(x)$ is a kernel estimator of the PDF (uniform kernel)
- Kernel is weight!
- There can be other kinds of kernel functions, when we assign different weights too different observations

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- A function can be used as a kernel if
 - = k(v) is symmetric with k(v) = k(-v)
- The weights sum to one; The weights are symmetric
- Triangular Kernel: $k(v) = (1 |v|)\mathbf{1}(|v| \le 1)$
- Epanechnikov Kernel: $k(v) = \frac{3}{4}(1-v^2)\mathbf{1}(|v| \le 1)$
- Gaussian Kernel: $k(v) = \frac{1}{2\pi}e^{\frac{-v'}{2}}$
- Usually, Epanechnikov Kernel and Triangular Kernel are preferred

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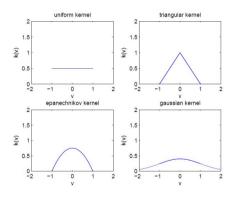


Figure 1: Various Kernels

- For multivariate case, let $v = (v_1, v_2, \dots, v_q)$
- Define product kernel: $K(v) = k(v_1)k(v_2)\cdots, k(v_q)$
- The estimator becomes

$$\hat{f}(x) = \frac{1}{nh_1h_2\cdots h_q} \sum_i K(\frac{X_i - x}{h})$$

- Define $h = (h_1, h_2, \dots, h_q)$
- $K(\frac{x_i-x}{h})$ is the weighted sum of points within the q-dimension hypercube
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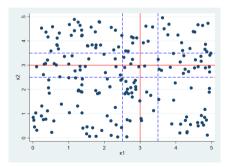
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In two dimension case, we have

- $K(\frac{X_i-x}{h})$ is the weighted sum of points within the rectangular
- h_1h_2 is the area of this rectangular



Step 3: Estimating a CEF

- Finally, let's see how to estimate a CEF using kernel method
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Homework

- 1. Derive NW Estimator from the kernel estimator of CDF and PDF. This can be a little bit hard. You can refer to Notes from Carol (or Hansen's book) for help.
- 2. What is NW Estimator, if we use the uniform kernel?

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Theorem (Asymptotics for N-W Estimator

Under some regularity conditions, as $n \to \infty, h_s \to 0$ (s = 1, ..., q), $nh_1 ... h_q \to \infty$ and $nh_1 ... h_q \sum_{s=1}^q h_s^6 \to 0$, we have:

$$\sqrt{nh_1...h_q}(\hat{g}(x) - g(x) - \sum_{s=1}^q h_s^2 B_s(x)) \stackrel{d}{\to} N(0, \frac{\sigma^2(x)}{f(x)} (\int k(v)^2 dv)^q)$$

where
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 ∴ we have trade-off in choosing kernel bandwidth
- (2) q ↑⇒ Variance ↑ exponentially (h is very small)
 We call this "Curse of Dimensionality".
- (3) Kernel more concentrated \Rightarrow Bias $\downarrow (\int v^2 k(v) dv = E(v^2))$, Variance $\uparrow (\int k(v)^2 dv)$)
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 - ⇒ The bias-variance tradeoff
- Given data, impossible to have lower bias and lower variance at the same time
- If you try to include more data points, variance ↓, but bias ↑
 - Expand bandwidth
 - Less concentrated kernel
- If you try to only use data points more nearby, bias ↓, but variance ↑
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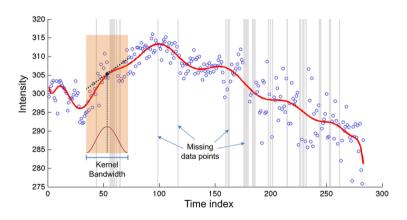
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For some X = x, we fit g(x) by choosing samples very close to x. Then we fit a polynomial for these observations. (Here, linear)

$$\min_{b_0,b_1,\cdots,b_p} \sum_{i=1}^n k(\frac{X_i - x}{h})(Y_i - b_0 - b_1(X_i - x) - b_2(X_i - x)^2 - \cdots - b_p(X_i - x)^p)^2$$

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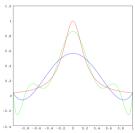
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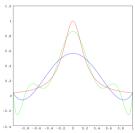
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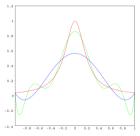
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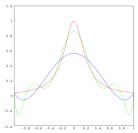
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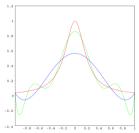
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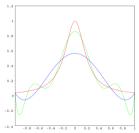
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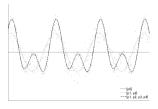
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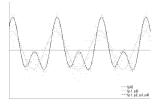
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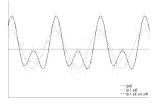
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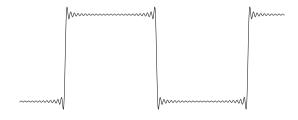
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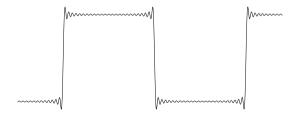


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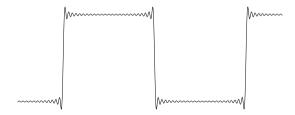
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- They are complicated, rarely seen in Applied works
- But Carol claims that Spline basis is in general a better choice
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Robinson, Peter M. 1988. "Root-N-consistent Semiparametric Regression." Econometrica: 931-954.